

section 2.2.

Linear Combinations

Definition

Consider in \mathbb{R}^3 the coordinate vectors $\vec{i} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $\vec{j} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ & $\vec{k} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$
Notice that any vector $v = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$ in \mathbb{R}^3 can be obtained from these 3 vectors:

$$v = \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ b \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ c \end{pmatrix} = a\vec{i} + b\vec{j} + c\vec{k}.$$

example

$$v = \begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix} = 2\vec{i} + 3\vec{j} - 1\vec{k} \quad (\text{we say that } v \text{ is obtained by adding scalar multiples of } \vec{i}, \vec{j}, \vec{k})$$

The vectors \vec{i}, \vec{j} & \vec{k} are not unique we may find another set of vectors v_1, v_2, v_3 where v can be written as sum of scalar multiples of v_1, v_2 & v_3 .

$$\text{example } v_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad v_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \quad v_3 = \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}$$

$$v = \begin{pmatrix} a \\ b \\ c \end{pmatrix} = c v_1 + (b-c) v_2 + (b-a) v_3 \Rightarrow v = \begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix} = -v_1 + 4v_2 + v_3.$$

definition 2.2.1 (Linear Combination)

let $S = \{v_1, v_2, \dots, v_k\}$ be a set of vectors in \mathbb{R}^n & let c_1, c_2, \dots, c_k be scalars in \mathbb{R} . a linear combination of the vectors of S is an expression of the form $c_1 v_1 + \dots + c_k v_k = \sum_{i=1}^k c_i v_i$
we say that a vector v is a linear combination of the vectors in S if $v = c_1 v_1 + \dots + c_k v_k$ for some c_1, c_2, \dots, c_k scalar in \mathbb{R}
example ($\Leftrightarrow \exists c_1, c_2, \dots, c_k \in \mathbb{R}$ such that $v = c_1 v_1 + \dots + c_k v_k$)

1] Determine whether $v = \begin{pmatrix} -1 \\ 1 \\ 10 \end{pmatrix}$ is a linear combination of $v_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$
 $v_2 = \begin{pmatrix} -2 \\ 3 \\ -2 \end{pmatrix}$ & $v_3 = \begin{pmatrix} -6 \\ 7 \\ 5 \end{pmatrix}$

2] Determine whether the vector $v = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ is a linear combination of $v_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$, $v_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$ & $v_3 = \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix}$

Answer

1] V lin Comb of $v_1, v_2, v_3 \iff \exists c_1, c_2, c_3$ scalars in $\mathbb{R} / c_1 v_1 + c_2 v_2 + c_3 v_3 = V$

$\iff \exists c_1, c_2, c_3$ scalar in $\mathbb{R} / c_1 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} -2 \\ 3 \\ -2 \end{pmatrix} + c_3 \begin{pmatrix} -6 \\ 7 \\ 5 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 10 \end{pmatrix}$

$\iff \exists c_1, c_2, c_3$ scalars in $\mathbb{R} / \begin{pmatrix} c_1 - 2c_2 - 6c_3 \\ 3c_2 + 7c_3 \\ c_1 - 2c_2 + 5c_3 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 10 \end{pmatrix}$

$\iff \exists c_1, c_2, c_3$ scalar in $\mathbb{R} / \begin{cases} c_1 - 2c_2 - 6c_3 = -1 \\ 3c_2 + 7c_3 = 1 \\ c_1 - 2c_2 + 5c_3 = 10 \end{cases}$

\iff The system $\left(\begin{array}{ccc|c} 1 & -2 & -6 & -1 \\ 0 & 3 & 7 & 1 \\ 1 & -2 & 5 & 10 \end{array} \right)$ is consistent.

Study Consistency of the system

$\left(\begin{array}{ccc|c} 1 & -2 & -6 & -1 \\ 0 & 3 & 7 & 1 \\ 1 & -2 & 5 & 10 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & -2 & -6 & -1 \\ 0 & 3 & 7 & 1 \\ 0 & 0 & 11 & 11 \end{array} \right) \Rightarrow$ the system is consistent

$\iff V$ lin combination of v_1, v_2, v_3 (not necessarily to solve the system)

to represent V as lin Comb of v_1, v_2, v_3 we need to find c_1, c_2 & c_3 & therefore solve the system \Rightarrow

$\begin{cases} c_1 - 2c_2 - 6c_3 = -1 \\ 3c_2 + 7c_3 = 1 \\ 11c_3 = 11 \end{cases} \Rightarrow \begin{matrix} c_3 = 1 \\ c_2 = -2 \\ c_1 = -4 + 6 - 1 = 1 \end{matrix} \Rightarrow V = v_1 - 2v_2 + v_3$

2] V linear combination of $v_1, v_2, v_3 \iff \exists c_1, c_2, c_3$ scalars in $\mathbb{R} / c_1 v_1 + c_2 v_2 + c_3 v_3 = V$

$\iff \exists c_1, c_2, c_3$ scalar in $\mathbb{R} / c_1 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + c_3 \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

$\iff \exists c_1, c_2, c_3$ scalar in $\mathbb{R} / \begin{pmatrix} c_1 + c_2 + 2c_3 \\ c_2 - c_3 \\ c_1 + 3c_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

$\iff \exists c_1, c_2, c_3$ scalar in $\mathbb{R} / \begin{cases} c_1 + c_2 + 2c_3 = 1 \\ c_2 - c_3 = 1 \\ c_1 + 3c_3 = 1 \end{cases}$

\iff the system $\left(\begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 0 & 1 & -1 & 1 \\ 1 & 0 & 3 & 1 \end{array} \right)$ is consistent

Study Consistency

$\left(\begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 0 & 1 & -1 & 1 \\ 1 & 0 & 3 & 1 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 0 & 1 & -1 & 1 \\ 0 & -1 & 1 & 0 \end{array} \right) \rightarrow \left(\begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 1 \end{array} \right)$ inconsistent

$\Rightarrow V$ is not a linear combination of v_1, v_2 & v_3 .

(Notice here that $v_3 = 3v_1 - v_2$ lin Comb of v_1 & v_2)

example 2.

The Coordinate vectors in \mathbb{R}^n : $e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \dots, e_n = \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix}$. $(e_i = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \rightarrow \text{UR comp})$
 any vector $v = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$ in \mathbb{R}^n can be written as a linear combination of $e_1, e_2, \dots, e_n \Rightarrow v = v_1 e_1 + \dots + v_n e_n$

example 3

show that the matrix $A = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$ is a linear combination of $M_1 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, M_2 = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}$ & $M_3 = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$

answer

A lin Comb of M_1, M_2 & $M_3 \iff \exists c_1, c_2$ & c_3 scalars in $\mathbb{R} / c_1 M_1 + c_2 M_2 + c_3 M_3 = A$
 $\iff \exists c_1, c_2, c_3$ scalars in $\mathbb{R} / c_1 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + c_2 \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} + c_3 \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$
 $\iff \exists c_1, c_2, c_3$ scalars in $\mathbb{R} / \begin{pmatrix} c_1 + c_3 & c_2 + c_3 \\ c_2 + c_3 & c_1 + c_2 + c_3 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$
 $\iff \exists c_1, c_2, c_3$ scalars in $\mathbb{R} / \begin{cases} c_1 + c_3 = 1 \\ c_2 + c_3 = 1 \\ c_2 + c_3 = 1 \\ c_1 + c_2 + c_3 = 0 \end{cases}$
 \iff the system $\left(\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 & 0 \end{array} \right)$ is consistent

study consistency

$\left(\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 & 0 \end{array} \right) \rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 & -1 & -1 \end{array} \right) \rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right) \rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$ consistent
 $c_3 = 2, c_2 = -1, c_1 = -1$

$\Rightarrow A = -M_1 - M_2 + 2M_3$

example 4

if y_1, y_2, \dots, y_k are k solutions of the homogenous linear system $AX=0$ show that any linear combination of y_1, y_2, \dots, y_k is also a solute of $AX=0$

Answer

let y be a lin combination of $y_1, y_2, \dots, y_k \iff \exists c_1, c_2, \dots, c_k \in \mathbb{R} / y = c_1 y_1 + \dots + c_k y_k$

show that y is a solution of $AX=0$ (ie show that $Ay=0$)

$Ay = A(c_1 y_1 + \dots + c_k y_k) \stackrel{\text{dist}}{=} A(c_1 y_1) + \dots + A(c_k y_k) = c_1 (Ay_1) + \dots + c_k (Ay_k)$ (properties of matrices)
 $= c_1 (0) + \dots + c_k (0)$ (since $Ay_i = 0 \forall i=1, \dots, k$)
 $= 0$ (y_i sol of $AX=0$)

$\Rightarrow y = c_1 y_1 + \dots + c_k y_k$ solute of $AX=0$

Important result

If y_1, y_2, \dots, y_k are solutions of $AX=0$ (homogenous linear system) then any linear combination of y_1, y_2, \dots, y_k is also a solution of $AX=0$

But this is not true for non homogenous linear systems $AX=b \neq 0$; if y_1, y_2, \dots, y_k are solutions of $AX=b \neq 0$
 $\nrightarrow y = c_1 y_1 + c_2 y_2 + \dots + c_k y_k$ solution of $AX=b$
 (to disprove take any numerical counter example)

Remark

Representation of the matrix multiplication AX with respect to the row vectors of A & with respect to the column vectors of A (A is any $m \times n$ matrix & X any $n \times 1$ vector)

(a) representation of AX with respect to the row vectors R_1, R_2, \dots, R_m of A

$$A \cdot X = \begin{pmatrix} R_1 \\ R_2 \\ \vdots \\ R_m \end{pmatrix} \cdot X = \begin{pmatrix} R_1 \cdot X \\ R_2 \cdot X \\ \vdots \\ R_m \cdot X \end{pmatrix}$$

(b) representation of AX with respect to the column vectors A_1, A_2, \dots, A_n of A (very important)

$$\begin{aligned} AX &= \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n \end{pmatrix} \\ &= \begin{pmatrix} a_{11}x_1 \\ a_{21}x_1 \\ \vdots \\ a_{m1}x_1 \end{pmatrix} + \begin{pmatrix} a_{12}x_2 \\ a_{22}x_2 \\ \vdots \\ a_{m2}x_2 \end{pmatrix} + \dots + \begin{pmatrix} a_{1n}x_n \\ a_{2n}x_n \\ \vdots \\ a_{mn}x_n \end{pmatrix} = \underbrace{\begin{pmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{pmatrix}}_{A_1} x_1 + \underbrace{\begin{pmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{pmatrix}}_{A_2} x_2 + \dots + \underbrace{\begin{pmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{pmatrix}}_{A_n} x_n \end{aligned}$$

$$\Rightarrow AX = x_1 A_1 + x_2 A_2 + \dots + x_n A_n$$

Therefore AX is a linear combination of the column vectors of A

Theorem 2.21.

Consider the $m \times n$ linear system $AX = b$

$AX = b$ is consistent \iff the vector b can be expressed as a linear combination of the column vectors of A

proof

Given $AX = b$ consistent \iff $AX = b$ has at least one solution

$\iff \exists$ at least one $x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$ solute of $AX = b$

by previous Remark any AX is a linear combination of the column vectors of A i.e. $AX = x_1 A_1 + x_2 A_2 + \dots + x_n A_n$.

$\iff \exists x_1, x_2, \dots, x_n \in \mathbb{R} / x_1 A_1 + x_2 A_2 + \dots + x_n A_n = b$

$\iff b$ is a linear combination of the column vectors A_1, A_2, \dots, A_n of A .